

# OPTIMIZING CAVITY GRADIENTS IN PULSED LINACS USING THE CAVITY TRANSIENT RESPONSE\*

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## Abstract

In order to achieve beam intensity and luminosity requirements, pulsed LINAC accelerators have stringent requirements on the amplitude and phase of RF cavity gradients. The amplitude and phase of the RF cavity gradients under heavy beam loading must be kept constant within a fraction of a % and a fraction of a degree respectively. The current paper develops a theoretical method to calculate RF parameters that optimize cavity gradients in multi cavity RF units under heavy beam loading. The theory is tested with a simulation example.

## INTRODUCTION

Modern pulsed LINAC accelerators are being designed taking advantage of the cost reduction that can be achieved powering a string of cavities from one klystron. At 70% peak power utilization a 10 MW klystron can power 24 superconducting cavities at an average gradient of 31.5MV/m and a beam current of 9mA. The XFEL main LINAC klystrons at DESY will power 32 cavities at 23.6MV/m and an average beam current of 5mA. As multiple cavities are connected to a single klystron the RF system parameters and control become more complex. A typical low level RF (LLRF) control loop controls the amplitude and the phase of the klystron's RF power, however, the loop cannot dynamically control individual cavity amplitude and phases. Typically, the control is done over the vector sum of all cavity gradients within the RF unit. The problem is further complicated by the need to obtain the maximum possible acceleration from the RF unit, pushing cavity gradients up close to their quenching limits. These cavity maximum gradients are different within a certain spread. Proton LINACs such as HINS [5] and Project X [6] add extra complexity to the RF system. A RF unit may need cavities operating at different synchronous phases ( $\Phi_s$ ). Secondly, particles travel cavities at increasing (non-relativistic) velocities, which implies different beam loading conditions from cavity to cavity.

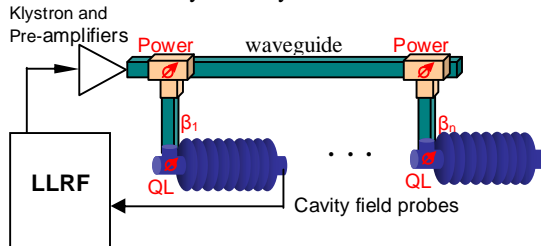


Figure 1.

Most of the literature available on cavity field dynamics follows a steady state approach [1-4]. The cavity is modeled by a 2nd order ODE (ordinary differential equation) and later approximated by a 1st order ODE model due to the high

loaded Q of the cavity. The steady state approach determines optimality conditions for minimum generator power as a function of the cavity coupling parameter  $\beta_{opt}$  and cavity tuning angle  $\phi_{opt}$ . The steady state analysis works well for continuous waveform (CW) machines. A similar steady state assumption is assumed about the beam, and these models use the average beam current.

The steady state analysis applied to pulsed RF Linacs does not provide optimum operation parameters for all cases. For cavities operating “on crest” ( $\Phi_s=0$ ) under heavy beam loading and strong RF coupling an exact calculation of the forward power and beam injection time can set constant cavity gradients (flattops) and minimize or zero out the reflected power. For “on crest” operation, gradient flattops can still be maintained for cavities operating at different gradients with one time optimization of the coupling parameter. Unfortunately, this is not longer valid when cavities in the same RF unit need to be operated at different synchronous phases. Moreover, as is the case for pulsed RF proton beam Linacs such as HINS [5] and Project X [6], cavities have different beam loading conditions. To exemplify the theory that will be developed in this paper we use one RF unit from the Project X proposal. The RF unit has 3 cryomodules with a total of 21 cavities operating with synchronous phases and beam loadings as described in Table 1. A typical  $\pm 10\%$  V<sub>cav</sub> spread is assumed.

Table 1.

Cavity Number	Beam Beta In	Beam Beta Out	Cavity Phase (degrees)	Cavity voltage (MV/m)
182	0.9196	0.9208	-20	23.22
183	0.9208	0.9220	-20	25.62
184	0.9220	0.9232	-20	24.90
185	0.9232	0.9243	-20	27.30
186	0.9243	0.9255	-20	23.46
187	0.9255	0.9266	-19	26.34
188	0.9266	0.9277	-19	24.66
189	0.9277	0.9288	-19	24.18
190	0.9288	0.9299	-19	26.58
191	0.9299	0.9309	-19	22.74
192	0.9309	0.9320	-18	27.54
193	0.9320	0.9330	-18	25.38
194	0.9330	0.9340	-18	24.42
195	0.9340	0.9350	-18	26.82
196	0.9350	0.9360	-18	25.86
197	0.9360	0.9370	-17	22.98
198	0.9370	0.9380	-17	23.94
199	0.9380	0.9389	-17	25.14
200	0.9389	0.9398	-17	23.70
201	0.9398	0.9407	-17	26.10
202	0.9407	0.9416	-16	27.06

The steady state optimization minimizes the klystron reflected power during beam-on time using [1-4]:

$$\beta_{opt} = 1 + \frac{2RI_{b0}}{V_{cav}} \cos \phi_s \quad \text{and} \quad \phi_{opt} = -\phi_s$$

Table 2 introduces the RF system parameters. For a description of these parameters see [1-4];

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Table 2.

Symbol	Definition
$\beta$	RF Coupling coefficient
$\Delta\omega$	Cavity detuning
$\omega_{12}$	Cavity half bandwidth
R	Cavity shunt impedance
$R_L$	Loaded resistance
$I_g$	Generator current
$I_b$	Beam current
$\theta$	Generator current phase

A simulation of the steady state optimum parameters using the RF unit example described above gives gradients and powers as shown in Figure 1. The simulator used is based on the 1<sup>st</sup> order dynamic models described in [1-4]. Also a  $\pm 10\%$  uniformly distributed maximum cavity gradient spread has been assumed around the required average cavity gradient for the RF unit. We observe that although the reflected power is small the individual cavity amplitudes and phases are neither constant nor close to the set-point values. Also the vectorsum (Fig.1a black trace) is far away from the vectorsum set-point (Fig.1a blue trace). As a consequence, when the feedback loop is closed the individual cavity gradients are further distorted to accommodate the vectorsum to the setpoint. The LLRF closed loop is unable to control cavity voltages to individual set-points because the system is uncontrollable at the individual set-point level.

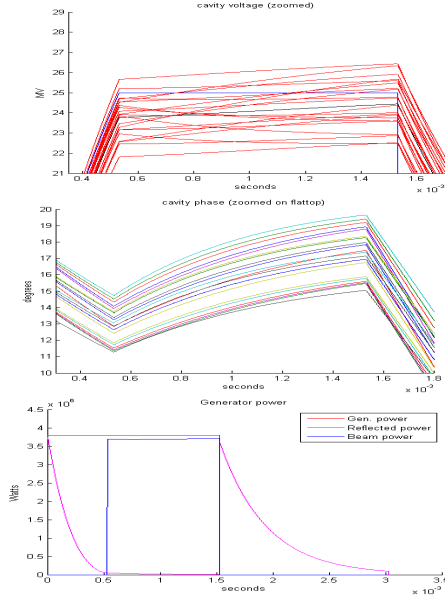


Figure 2 a) Cavity, vectorsum and vectorsum setpoint amplitude voltages, b) cavity phases, c) RF forward, reflected and beam powers.

## TRANSIENT ANALYSIS

The RF system voltages and currents are modeled by

$$V(t) = V_A(t) \cdot e^{j(\omega t + \phi(t))} = (V_r(t) + jV_i(t)) \cdot e^{j\omega t} \quad (1)$$

$$I(t) = I_A(t) \cdot e^{j(\omega t + \phi(t))} = (I_r(t) + jI_i(t)) \cdot e^{j\omega t}$$

The RF voltages and currents in (1) are modulated in amplitude and phase. The LLRF controls the slow dynamics of the RF amplitude and phase called the RF envelope. The

RF envelope is typically modeled by a 1<sup>st</sup> order ODE in the complex space  $C^1$  [4].

$$\dot{V}_{cav}(t) = AV_{cav}(t) + BI_{tot}(t), \quad (2)$$

As said, V and I are complex numbers, and

$$A = \begin{pmatrix} -\omega_{12} & -\Delta\omega \\ \Delta\omega & -\omega_{12} \end{pmatrix}, \quad B = \begin{pmatrix} R_L\omega_{12} & 0 \\ 0 & R_L\omega_{12} \end{pmatrix}$$

Since the system is linear, the cavity voltage is the superposition of the cavity response to the generator and beam currents (power)  $I_g e^{j\theta}$  and  $I_b e^{j\pi}$ . The current equations assume the convention that the phase is zero for the negative of the beam current.

The solution to equation (2) is given by:

$$\begin{pmatrix} V_r \\ V_i \end{pmatrix} = \frac{\omega_{12} R_L}{\omega_{12}^2 + \Delta\omega^2} \left\{ e^{-\omega_{12} t} I_g \begin{pmatrix} -\omega_{12} \cos(\Delta\omega t + \theta) + \Delta\omega \sin(\Delta\omega t + \theta) \\ -\Delta\omega \cos(\Delta\omega t + \theta) - \omega_{12} \sin(\Delta\omega t + \theta) \end{pmatrix} u(t) + I_b \begin{pmatrix} \omega_{12} \cos\theta - \Delta\omega \sin\theta \\ \Delta\omega \cos\theta + \omega_{12} \sin\theta \end{pmatrix} u(t) - e^{-\omega_{12}(t-t_0)} I_b \begin{pmatrix} -\omega_{12} \cos\Delta\omega(t-t_0) + \Delta\omega \sin\Delta\omega(t-t_0) \\ -\Delta\omega \cos\Delta\omega(t-t_0) - \omega_{12} \sin\Delta\omega(t-t_0) \end{pmatrix} u(t-t_0) - I_b \begin{pmatrix} \omega_{12} \\ \Delta\omega \end{pmatrix} u(t-t_0) \right\} \quad (3)$$

Where  $u(t)$  is the Heaviside function (i.e.  $u(t)=1$   $t \geq 0$  and 0 otherwise).

To obtain a flattop at the injection time  $t=t_0$  we must eliminate the time dependency in equation (3). That is achieved by making

$$I_g = e^{\omega_{12} t_0} I_b \quad (4) \quad \text{and} \quad \Delta\omega = -\frac{\theta}{t_0} \quad (5)$$

Equations (4) and (5) guarantee a flattop for  $t \geq t_0$ . The appropriate value for the flattop amplitude and phase can be obtained from equation (3) at  $t=t_0$ . This is given by

$$\begin{pmatrix} V_r \\ V_i \end{pmatrix}_{t=t_0} = \frac{\omega_{12} R_L}{\omega_{12}^2 + \Delta\omega^2} \left\{ e^{-\omega_{12} t_0} I_g \begin{pmatrix} -\omega_{12} \\ -\Delta\omega \end{pmatrix} + I_g \begin{pmatrix} \omega_{12} \cos\theta - \Delta\omega \sin\theta \\ \Delta\omega \cos\theta + \omega_{12} \sin\theta \end{pmatrix} \right\} \quad (6)$$

Using the tuning angle equation  $\tan\psi = \frac{\Delta\omega}{\omega_{12}}$ , the complex cavity voltage in (6) can be by its amplitude and phase

$$|V_c| = \frac{R_L I_b}{1 + \tan^2\psi} \sqrt{\left( -1 + e^{\omega_{12} t_0} (\cos\theta - \tan\psi \sin\theta) \right)^2 + \dots + \left( -\tan\psi + e^{\omega_{12} t_0} (\tan\psi \cos\theta + \sin\theta) \right)^2} \quad (7)$$

$$\phi_s = \tan^{-1} \left( \frac{\tan\psi \cos\theta + \sin\theta - \tan\psi e^{-\omega_{12} t_0}}{\cos\theta - \tan\psi \sin\theta - e^{-\omega_{12} t_0}} \right) \quad (8)$$

Equations (7) and (8) have 3 degrees of freedom in the RF system phase space  $\theta$  (or  $\psi$ ),  $\beta$  and  $t_0$ . Both  $R_L$  and the half bandwidth of the cavity  $\omega_{12}$  are a function of  $\beta$ . In a multi cavity RF unit, individual cavity flattops can be set calculating individual cavity values  $\theta_{cav}$  and  $\beta_{cav}$  that satisfy (7) and (8) with (constraints (4) and (5) for a given  $t_0$ . However,  $t_0$ , the beam-on time, is unique for the RF unit and constrains the generator (reflected) power. Hence, to minimize the overall power requirements in an N cavity RF unit a system of 2·N equations with 2·N+1 unknowns must be solved.

## RF POWER OPTIMIZATION

The reflected power is given by

$$P_{ref} = P_{gen} - \frac{dW}{dt} - P_{beam} - P_{diss}, \quad \text{where}$$

$P_{ref}$ : reflected power.

$P_{gen}$ : generator power

$P_{beam}$ : power transferred to the beam.

$dW/dt$ : change of stored energy in the cavity.

$P_{diss}$ : cavity cryogenic losses.

For superconducting cavities  $P_{diss}$  is very small compared to the other members and can be neglected. If (6) and (7) are

able to achieve a good flattop then  $dW/dt$  is also very small. Then we can approximate  $P_{ref} \approx P_{gen} - P_{beam}$  and the reflected power is given by the mismatch between the RF system characteristic impedance and the cavity-beam impedance reflected to the waveguide (Fig 2).

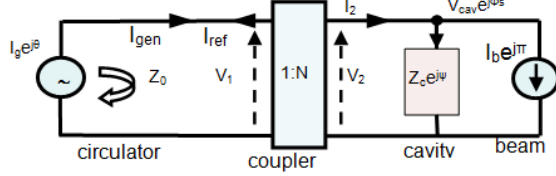


Figure 2

The cavity-beam impedance is given by the parallel

$$Z_{eq} = Z_{cav} // Z_{beam} = Z_c e^{j\psi} // \frac{V_{cav} e^{-j\phi_s}}{I_b} \quad (9)$$

Minimizing the reflected power implies  $Z_{eq}/N^2$  that should be a close match of  $Z_0$ . Given that  $Z_0$  is real, the imaginary part of  $Z_{eq}$  should be minimized and the real part of  $Z_{eq}$  reflected to the waveguide side should match  $Z_0$ .

## OPTIMIZATION AND SIMULATION EXAMPLE

The nonlinear system given by (7), (8) and (9) with constraints given by (4) and (5) for each cavity can be solved to find an optimum set of parameters  $\beta_i^{opt}$ ,  $\psi_i^{opt}$  (or  $\theta_i^{opt}$ ), and  $t_0^{opt}$ . As an example of the method described above we have used the same Project X RF unit described in Table I. The nonlinear system of equations has been solved using a numerical solver from Matlab. The optimized parameters were fed to the same RF unit simulator used to generate Figure 1. Figure 3 shows that the cavity gradients using the transient approach have been substantially improved both for amplitude and phase. This improvement to the individual cavity gradients is done at the cost of increasing the reflected power with respect to the steady state approach during the beam-on to about 4% of the beam power.

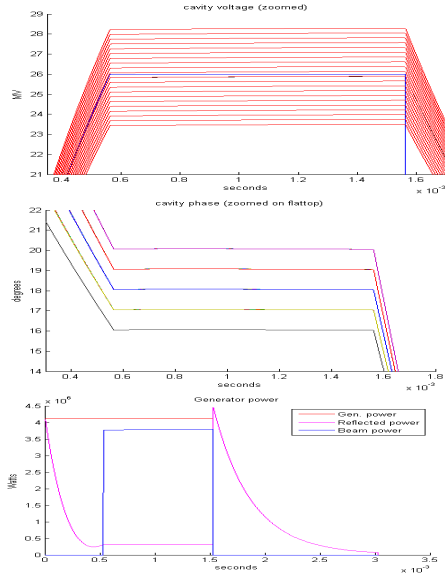


Figure 3 a) Cavity, vectorsum and vectorsum setpoint

amplitude voltages, b) cavity phases, c) RF forward, reflected and beam powers.

## CONCLUSIONS

The transient analysis allows optimum cavity gradient flattops across the RF unit, in particular when those cavities are operated at different synchronous phases ( $\Phi_i$ ) and with different beam loading conditions. The optimum RF parameters  $\beta_i^{opt}$ ,  $\psi_i^{opt}$  only need to be set once during the RF and beam commissioning and are not coupled with parameters in other cavities in the RF unit. The beam-on time  $t_0^{opt}$  can be used to minimize the RF generator power. For the sake of comparison Table 3 shows the optimization parameters obtained by each method.

Table 3.

Cavity Number	Steady state		Transient	
	Beta	Theta	Beta	Theta
182	2942	-20.00°	3473	-35.54°
183	2692	-20.00°	4184	-34.77°
184	2797	-20.00°	3881	-35.10°
185	2574	-20.00°	4540	-34.40°
186	3021	-20.00°	3257	-35.79°
187	2731	-19.00°	4109	-33.11°
188	2940	-19.00°	3515	-33.72°
189	3022	-19.00°	3292	-33.96°
190	2770	-19.00°	3993	-33.23°
191	3262	-19.00°	2663	-34.66°
192	2728	-18.00°	4151	-31.33°
193	2981	-18.00°	3439	-32.03°
194	3119	-18.00°	3071	-32.40°
195	2858	-18.00°	3781	-31.69°
196	2982	-18.00°	3436	-32.03°
197	3395	-17.00°	2398	-31.28°
198	3278	-17.00°	2691	-30.98°
199	3140	-17.00°	3049	-30.63°
200	3348	-17.00°	2516	-31.16°
201	3055	-17.00°	3272	-30.41°
202	2977	-16.00°	3515	-28.40°

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